

Reference Specifications

No: 01100212

KC100 INCREMENTAL

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1. KC100 Incremental Optical Encoder (Through shaft+keyway)

1.1 Introduction:

KC100 is a through shaft keyway encoder that can output incremental signals. It has a compact and durable structure and is widely used in motors, elevators and industrial automation fields.

KC100-C

KC100-T

1.2 Feature:

- Encoder external diameter Ø100mm, thickness 30mm, diameter of shaft up to Ø40mm;
- · Flexible spring plate installation,
- Adopt non-contact photoelectric principle;
- · Reverse polarity protection;
- · Short circuit protection,
- · Multiple electrical interfaces available;
- Resolution per turn up to 100000PPR.

1.3 Application:

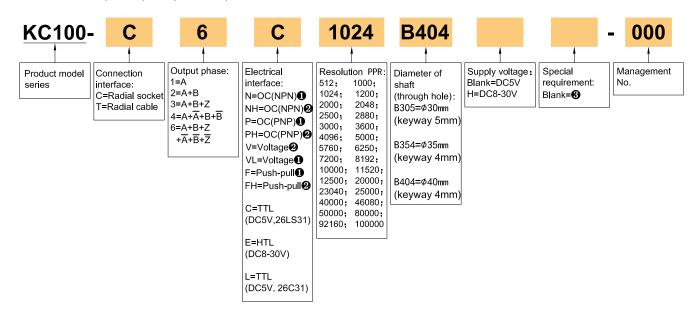
Elevator, motor, packaging machinery, CNC and other automation control fields.

- 1.4 Connection:
 - Radial socket
 - Radial cable (standard length 1M)
- 1.5 Protection: IP50
- 1.6 Weight: About 670g



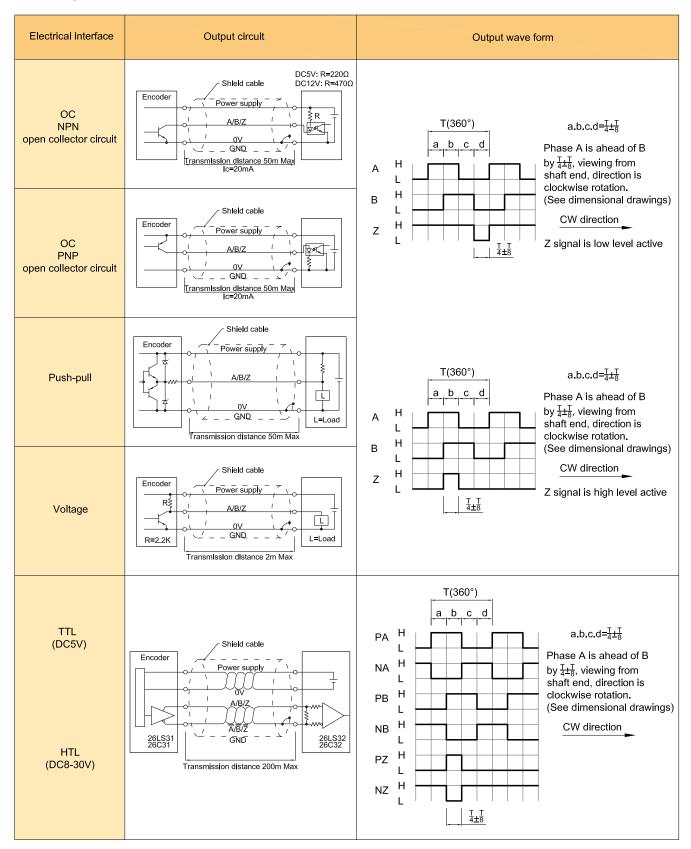
2. Model Selection Guide

2.1 Model composition(select parameters)



- 2. 2 Note
- 1. Z signal is low level active.
- 2. Z signal is high level active.
- None indicated for IP50, the cable length is 1M, if need to change the length C+number, the longest is 100M (expressed by C100). For the specific length of use, pls refer to page 2 of the provision of output circuit.

3. Output Method



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Parameter Output type			oc	Voltage	Push-pull	ΠL	HTL			
Sup	Supply voltage		DC5V±5%; DC8V-30V	′±5%	DC5V±5%	DC8-30V±5%				
Cor	Consumption current		100mA Max		120mA Max					
	Allowable ripple		≤3%rms							
Top	respons Juency	е	100KHz		300KHz	500KHz				
	Output Inpu		≤30mA	d	≤30mA	≤±20mA	≤±50mA			
acity	current	Output	_	Load resistance 2.2K	≤10mA	SIZUMA	SISUMA			
t cap	Output voltage	"H"	_	_	≥[(Supply voltage)-2.5V]	≥2.5V	≥Vcc-3 Vpc			
Output capacity		"L"	≤0.4V	≤0.7V(less than 20mA)	≤0.4V(30mA)	≤0.5V	≤1V VDC			
0	Load voltage		≤DC30V	_		_				
Ris	e & Fall ti	me	Less than 2us(cable ler	ngth: 2m)	Less than 1us(Cable length: 2m)					
Insu	lation str	ength	AC500V 60s							
Insu	lation stance		10ΜΩ							
Mar	k to space	e ratio	45% to 55%							
Rev	Reverse polarity protection		V							
	Short-circuit protection		v0							
Pha	Phase shift between A & B		90°±10° (frequency in low speed)							
betv			90°±20° (frequency in high speed)							
GNI	GND		Not connect to encoder							

① Short-circuit to another channel or GND permitted for max.30s.

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Diameter of shaft	Ø30mm(keyway 5); Ø35mm(keyway 4); Ø40mm(keyway 4); material stainless steel
Starting torque	Less than 98×10 ⁻³ N⋅m
Inertia moment	Less than 120×10 ⁻⁶ kg·m²
Shaft load	Radial 90N; Axial 60N
Slew speed	≤3000 rpm
Bearing Life	1.5X10 ⁹ revs at rated load(100000hrs at 2500RPM)
Shell	Die cast aluminum
Weight	about 670g

6. Environmental Parameters

Environmental temperature	Operating: -20~+85°C(repeatable winding cable: -10°C); Storage: -25~+90°C
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(Endurance)	Amplitude 0.75mm,5~55Hz,2h for X,Y,Z direction individually
Shock(Endurance)	1960m/s ² 11ms three times for X,Y,Z direction individually
Protection	IP50

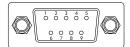
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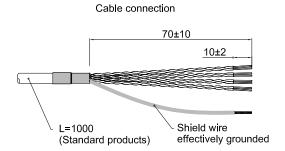
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7. Wiring Table

DB-9P male socket pin distribution diagram





7.1 OC/Voltage/Push-pull (Wiring table for socket connection and cable connection)

	Supply voltage		Incremental signal						
Socket pin definition	1	2	3	4	5	6	7	8	9
Wire color	Red	Black	White	Green	Yellow	1	/	/	1
Function	Up	Un	А	В	Z	/	/	/	/

7.2 TTL/HTL(Wiring table for socket connection and cable connection)

	Supply voltage		Incremental signal						
Socket pin definition	1	2	3	6	4	7	5	8	9
Wire color	Red	Black	White	White/BK	Green	Green/BK	Yellow	Yellow/BK	1
Function	Up	Un	A+	A-	B+	B-	Z+	Z-	/
Twisted-paired cable									

Up=Supply voltage.

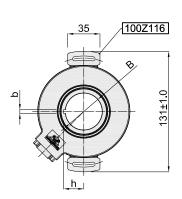
Shield wire is not connected to the internal circuit of encoder.

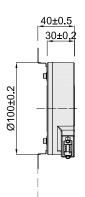
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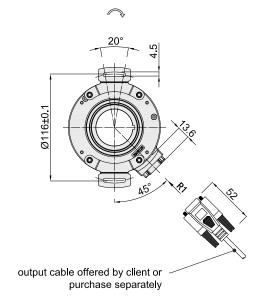
8. Basic Dimensions

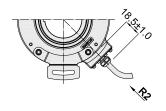
8.1 Dimensions



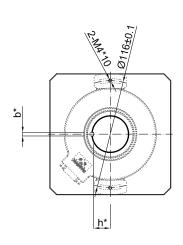


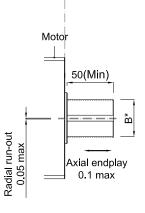
Encoder shaft diameter tolerances						
В	b	h				
Ø30 ^{H7} (^{+0.034} _{+0.009})	5 ^{+0.078} _{+0.030}	17.3 ^{+0.1}				
Ø35 ^{H7} (^{+0.034} _{+0.009})	4 ^{+0.078} _{+0.030}	19.3 ^{+0.1}				
Ø40 ^{H7} (+0.034)	4 ^{+0.078} _{+0.030}	21.8 +0.1				





8.2 Mounting shaft requirements





Motor shaft diameter tolerance					
B* b* h*					
$Ø30_{g6}(^{-0.009}_{-0.025})$	5 ^{H9} (^{+0.036} ₀)	12.01			
Ø35 _{g6} (-0.009)	$4^{H9}(^{+0.036}_{0})$	15.01			
$\emptyset40_{g6}(^{0.009}_{0.025})$	4 ^{H9} (^{+0.036})	17.5 0 1			

Mounting screws
Inner hexagon bolt
+flat washer
Specification: M4*8
Material: stainless steel
Quantity: 2

Unit: mm



= Shaft rotation direction of the incremental signal output

R.1 = Radial socket (DB-9P 9pin male socket)

R.2 = Radial cable (standard length 1M)

About vibration

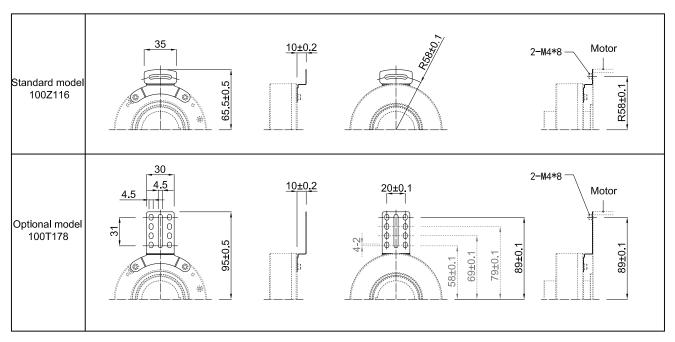
Vibration act on encoder always cause wrong pulse, so we should pay attention to working place. More pulse per revolution, narrower groovy spacing of grating, more effect to encoder by vibration, when rev is low or stop, vibration act on shaft or main body would cause grating vibrating, so encoder might make wrong pulse.

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9. recommended accessories

9.1 Spring plate options



9.2 Recommended plugs and cables

Plug and cable	Brief description	No.	Order No.
	C1=Connection type head A: DB-9P female straight connector; Connection type head B: Bare wire end; Cable length: 1M 8-core with shield,halogen-free PUR	K100C1	44400048
at least	C2=Connection type head A: DB-9P female straight connector; Connection type head B: Bare wire end; Cable length: 2M 8-core with shield,halogen-free PUR	K100C2	44400049
	C5=Connection type head A: DB-9P female straight connector; Connection type head B: Bare wire end; Cable length: 5M 8-core with shield,halogen-free PUR	K100C5	44400050



Tel: 86-21-54613487