## S50 INCREMENTAL

## 1. S50 Incremental Optical Encoder (Solid shaft)

1.1 Introduction:

S50 is a robust universal solid shaft design, compact, durable and safe, commonly used in industrial automation.
1.2 Feature:

- Encoder external diameter $\varnothing 50 \mathrm{~mm}$, thickness 30 mm , diameter of shaft $\varnothing 8 \mathrm{~mm}$ (D type);
- Adopt non-contact photoelectric principle;
- Reverse polarity protection;
- Short circuit protection;
- Multiple electrical interfaces available;
- Resolution per turn up to 48000PPR.
1.3 Application:

Textile, packaging, motor, elevator, CNC and other automation control fields.

4 Connection:

- Radial cable (standard length 1M)
- Axial cable (standard length 1M)
- Axial socket (binder, 682 series)
1.5 Protection: IP50 \& IP65
1.6 Weight: about 190g


## 2. Model Selection Guide

2.1 Model composition(select parameters)

2. 2 Note
(1.) $Z$ signal is low level active.
(2. $Z$ signal is high level active.
(3. None indicated for IP50 and cable length of 1 M , if need to change the length $\mathrm{C}+$ number, the longest is 100 M (expressed by C100). For the specific length of use, pls refer to page 2 of the provision of output circuit.

## 3. Output Mode



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## 4. Electrical Parameters

|  |  |  | OC | Voltage | Push-pull | TTL | HTL |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Supply voltage |  |  | DC $+5 \mathrm{~V} \pm 5$ | $\pm 5 \%$ |  | DC $+5 \mathrm{~V} \pm 5 \%$ | DC8-30V $\pm 5 \%$ |
| Consumption current |  |  | 100mA Max |  |  | 120mA Max |  |
| Allowable ripple |  |  | $\leq 3 \% \mathrm{rms}$ |  |  |  |  |
| Top responsefrequency |  |  | 100 KHz |  |  | 300 KHz | 500 KHz |
|  | Output | Input | $\leq 30 \mathrm{~mA}$ | Load resistance$2.2 \mathrm{~K}$ | <30mA | $\leq \pm 20 \mathrm{~mA}$ | $\leq \pm 50 \mathrm{~mA}$ |
|  | current | Output | - |  | $\leq 10 \mathrm{~mA}$ |  |  |
|  | Output voltage | "H" | - | - | $\begin{aligned} & \geq[\text { (Supply voltage) } \\ & -2.5 \mathrm{~V}] \end{aligned}$ | $\geq 2.5 \mathrm{~V}$ | $\geq \mathrm{Vcc}-3 \mathrm{Vdc}$ |
|  |  | "L" | <0.4V | $\leq 0.7 \mathrm{~V}$ (less than 20 mA ) | $\leq 0.4 \mathrm{~V}(30 \mathrm{~mA})$ | $\leq 0.5 \mathrm{~V}$ | $\leq 1 \mathrm{~V}$ VDC |
|  | Load voltage |  | $\leq$ DC30V | - |  | - |  |
| Rise \& Fall time |  |  | Less than 2us(cable length: 2m) |  |  | <100ns Les | (Cable length: 2 m ) |
| Insulation strength |  |  | AC500V 60s |  |  |  |  |
| Insulation resistance |  |  | $10 \mathrm{M} \Omega$ |  |  |  |  |
| Mark to space ratio |  |  | 45\% to 55\% |  |  |  |  |
| Reverse polarity protection |  |  | $\checkmark$ |  |  |  |  |
| Short-circuit protection |  |  | - |  | $\boldsymbol{\sim}$ (1) |  |  |
| Phase shift between A \& B |  |  | $90^{\circ} \pm 10^{\circ}$ ( frequency in low speed) |  |  |  |  |
|  |  |  | $90^{\circ} \pm 20^{\circ}$ ( frequency in high speed) |  |  |  |  |
| GND |  |  | Not connect to encoder |  |  |  |  |

(1) Short-circuit to another channel or GND permitted for max 30s.

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## 5. Mechanical Specifications

| Diameter of shaft | $\varnothing 8 \mathrm{~mm}$ (D type, stainless steel material) |
| :--- | :--- |
| Starting torque | Less than $5 \times 10^{-3} \mathrm{~N} \cdot \mathrm{~m}$ |
| Inertia moment | Less than $3 \times 10^{-6} \mathrm{~kg} \cdot \mathrm{~m}^{2}$ |
| Shaft load | Radial $40 \mathrm{~N} ;$ Axial 20 N |
| Slew speed | $\leq 6000 \mathrm{rpm}(\mathrm{IP50}) ; \leq 4000 \mathrm{rpm}(\mathrm{IP65})$ |
| Bearing Life | $1.5 \times 10^{9}$ revs at rated load(100000hrs at 2500RPM) |
| Shell | Aluminium alloy |
| Weight | about 190 g |

## 6. Environmental Parameters

| Environmental temperature | Operating: $-20 \sim+90^{\circ} \mathrm{C}$ (repeatable winding cable: $-10^{\circ} \mathrm{C}$ ); Storage: $-25 \sim+95^{\circ} \mathrm{C}$ |
| :--- | :--- |
| Environmental humidity | Operating and storage: $35 \sim 85 \% \mathrm{RH}$ (noncondensing) |
| Vibration(Endurance) | Amplitude $0.75 \mathrm{~mm}, 5 \sim 55 \mathrm{~Hz}, 2 \mathrm{~h}$ for $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ direction individually |
| Shock(Endurance) | $490 \mathrm{~m} / \mathrm{s}^{2} 11 \mathrm{~ms}$ three times for $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ direction individually |
| Protection | IP50 \& IP65 |

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## 7. Wiring table

7.1 OC/Voltage/Push-pull (Wiring table for socket and cable connection)

|  | Supply voltage |  | Incremental signal |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Socket pin number | 1 | 2 | 3 | 4 | 5 |
| Wire color | Red | Black | White | Green | Yellow |
| Function | Up | $0 V$ | $A$ | $B$ | $Z$ |

7.2 TTL/HTL (Wiring table for socket and cable connection)

|  | Supply voltage |  | Incremental signal |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Socket pin number | 1 | 2 | 3 | 6 | 4 | 7 | 5 | 8 |
| Wire color | Red | Black | White | White/BK | Green | Green/BK | Yellow | Yellow/BK |
| Function | Up | OV | A+ | A- | B+ | B- | Z+ | Z- |
| Twisted-paired cable |  |  |  |  |  |  |  |  |

## Up=Supply voltage.

Shield wire is not connected to the internal circuit of encoder.

Cable connection


Axial socket connection


M16-8DIN pin male socket pin assignment diagram

## 8. Basic Dimensions

### 8.1 S50-T


8.2 S50-Q

8.3 S50-D


Socket model: (682 series, M16-8DIN flange socket)


Pin 1=DC
$2=0 \mathrm{~V}$
$3=A$
4=B
5=Z
$6=\overline{\mathrm{A}}$
$7=\bar{B}$
$8=\bar{Z}$

Unit: mm

$\Omega=$ Shaft rotation direction of incremental signal output
R. 1 = Radial cable (standard length 1 M )
A. 1 = Axial cable (standard length 1 M )
A. 2 = Axial socket (M16-8DIN)

About vibration
Vibration act on encoder always cause wrong pulse, so we should pay attention to working place.More pulse per revolution, narrower groovy spacing of grating, more effect to encoder by vibration, when rev is low or stop, vibration act on shaft or main body would cause grating vibrating, so encoder might make wrong pulse.

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9. Accessories(Recommended purchase)
9.1 Coupling

9.2 Mounting bracket
S50-50L30 No : 03500165

