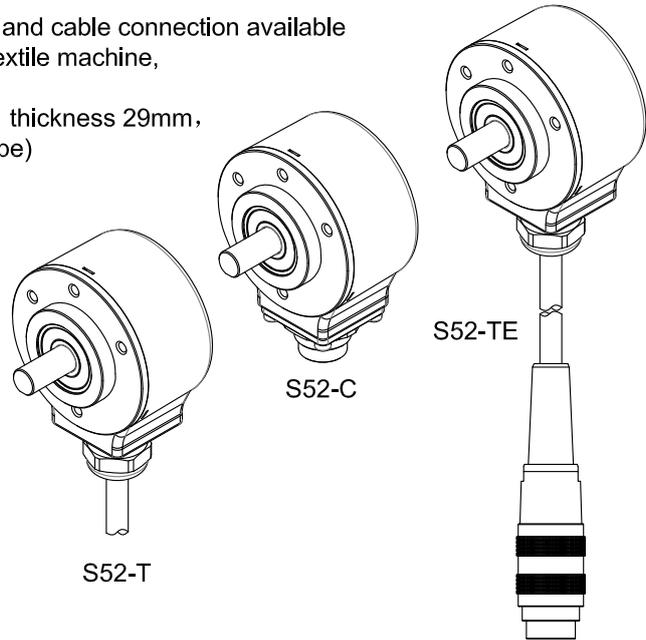


# S52

## Specifications 1/7

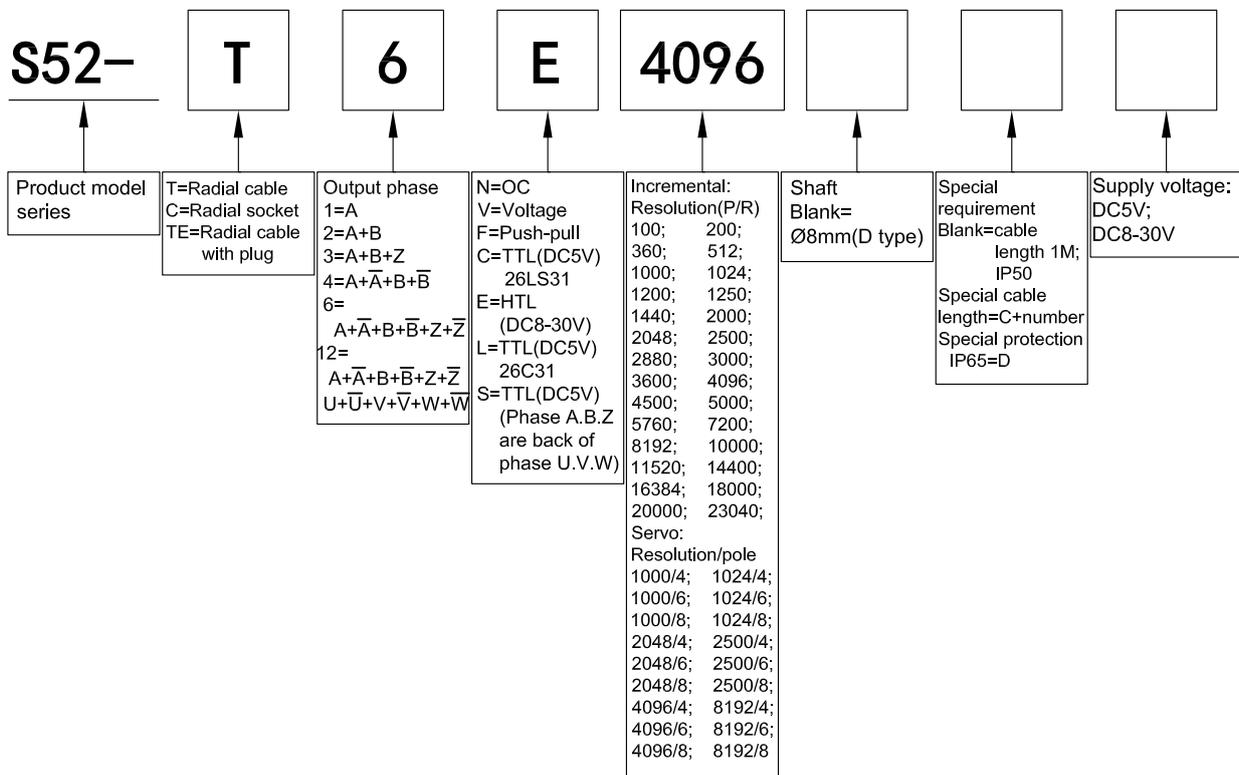
### Incremental Type(Solid Shaft)

- Feature: sturdy and durable, various circuit mode and cable connection available
- Application: automation control like motor, CNC, textile machine, industrial assembly line, etc.
- External dimensions: external diameter  $\varnothing 51\text{mm}$ , thickness 29mm, diameter of shaft 8mm(D type)
- Resolution: Max to 23040ppr
- Supply voltage: DC5V; DC8-30V
- Protection: IP50; IP65
- Cable length: 1000mm
- Weight: about 300g



### Model Guide

- Model form (filled required parameters in the box as following)
- Must choose supply voltage: DC5V; DC8-30V
- If need coupling and bracket, please purchase additionally (accessory at specifications 6/6)



Output Mode

Output type	Output circuit	Output wave form	Connection
OC		<p> <math>a.b.c.d = \frac{T}{4} \pm \frac{T}{8}</math>                      Phase A is ahead of B by <math>\frac{T}{4} \pm \frac{T}{8}</math>, rotate direction CW (View from shaft end, direction is clockwise rotation)                      CW direction <math>\rightarrow</math> </p>	0=GND 1=red=DC5V; DC8-30V 2=black=OV 3=white=A 4=green=B 5=yellow=Z
Push-Pull		<p> <math>a.b.c.d = \frac{T}{4} \pm \frac{T}{8}</math>                      Phase A is ahead of B by <math>\frac{T}{4} \pm \frac{T}{8}</math>, rotate direction CW (View from shaft end, direction is clockwise rotation)                      CW direction <math>\rightarrow</math> </p>	
Voltage		<p> <math>a.b.c.d = \frac{T}{4} \pm \frac{T}{8}</math>                      Phase A is ahead of B by <math>\frac{T}{4} \pm \frac{T}{8}</math>, rotate direction CW (View from shaft end, direction is clockwise rotation)                      CW direction <math>\rightarrow</math> </p>	
TTL		<p> <math>a.b.c.d = \frac{T}{4} \pm \frac{T}{8}</math>                      Phase A is ahead of B by <math>\frac{T}{4} \pm \frac{T}{8}</math>, rotate direction CW (View from shaft end, direction is clockwise rotation)                      CW direction <math>\rightarrow</math> </p>	0=shielding=GND 1=red=DC5V; DC8-30V 2=black=OV 3=white=A 4=green=B 5=yellow=Z 6=white/black= $\bar{A}$ 7=green/black= $\bar{B}$ 8=yellow/black= $\bar{Z}$
HTL		<p> <math>\frac{T}{4} \pm \frac{T}{8}</math> </p>	

# S52

## Specifications 3/7

● Output Mode

Output type	Output circuit	Output wave form	Connection																																																																		
TTL		<p> <math>a, b, c, d = \frac{T}{4} \pm \frac{T}{8}</math>  <math>e = T \pm \frac{T}{2}</math>                      f: center of phase Z to rise point of phase U, that is <math>\pm 0.3^\circ</math> </p> <p>CCW direction → (Viewed from shaft end when installing)</p>	0=shielding=GND 1=A=red=DC5V 2=C=black=OV 3=E=white=A 4=G=green=B 5=J=yellow=Z 6=L=white/black= $\bar{A}$ 7=M=green/black= $\bar{B}$ 8=N=yellow/black= $\bar{Z}$ 9=O=blue=U 10=P=grey=V 11=R=pink=W 12=S=blue/black= $\bar{U}$ 13=T=grey/black= $\bar{V}$ 14=U=pink/black= $\bar{W}$																																																																		
TTL (phase A,B,Z are back of phase U,V,W)	<table border="1"> <thead> <tr> <th>pole</th> <th>g,h,j,k,m,n</th> <th>r</th> </tr> </thead> <tbody> <tr> <td>4</td> <td><math>30 \pm 1^\circ</math></td> <td><math>180^\circ</math></td> </tr> <tr> <td>6</td> <td><math>20 \pm 1^\circ</math></td> <td><math>120^\circ</math></td> </tr> <tr> <td>8</td> <td><math>15 \pm 1^\circ</math></td> <td><math>90^\circ</math></td> </tr> </tbody> </table>	pole	g,h,j,k,m,n	r	4	$30 \pm 1^\circ$	$180^\circ$	6	$20 \pm 1^\circ$	$120^\circ$	8	$15 \pm 1^\circ$	$90^\circ$	<p> <math>a, b, c, d = \frac{T}{4} \pm \frac{T}{8}</math>  <math>e = T \pm \frac{T}{2}</math>                      f: center of phase Z to rise point of phase U, that is <math>\pm 0.3^\circ</math> </p> <p>CCW direction → (Viewed from shaft end when installing)</p>	<table border="1"> <thead> <tr> <th rowspan="2">No.</th> <th rowspan="2">Function</th> <th colspan="3">Mode</th> </tr> <tr> <th>Color</th> <th>1</th> <th>2</th> <th>3</th> </tr> </thead> <tbody> <tr> <td>3</td> <td>white</td> <td>HZ</td> <td>U</td> <td>A</td> </tr> <tr> <td>6</td> <td>white/black</td> <td>HZ</td> <td><math>\bar{U}</math></td> <td><math>\bar{A}</math></td> </tr> <tr> <td>4</td> <td>green</td> <td>HZ</td> <td>V</td> <td>B</td> </tr> <tr> <td>7</td> <td>green/black</td> <td>HZ</td> <td><math>\bar{V}</math></td> <td><math>\bar{B}</math></td> </tr> <tr> <td>5</td> <td>yellow</td> <td>HZ</td> <td>W</td> <td>Z</td> </tr> <tr> <td>8</td> <td>yellow/black</td> <td>HZ</td> <td><math>\bar{W}</math></td> <td><math>\bar{Z}</math></td> </tr> <tr> <td>1</td> <td>red</td> <td colspan="3">DC+5V</td> </tr> <tr> <td>2</td> <td>black</td> <td colspan="3">OV</td> </tr> <tr> <td>0</td> <td>shielding</td> <td colspan="3">GND</td> </tr> </tbody> </table>	No.	Function	Mode			Color	1	2	3	3	white	HZ	U	A	6	white/black	HZ	$\bar{U}$	$\bar{A}$	4	green	HZ	V	B	7	green/black	HZ	$\bar{V}$	$\bar{B}$	5	yellow	HZ	W	Z	8	yellow/black	HZ	$\bar{W}$	$\bar{Z}$	1	red	DC+5V			2	black	OV			0	shielding	GND		
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<p>Timing Chart</p> <p>                     Supply voltage: <math>5 \pm 0.25</math>, <math>4.25 \pm 0.3</math>                      Instantaneous power down                      Power off                      Power on                      Time(msec)                 </p> <p>                     Mode: 1, 2, 3                      510±220, 22±11, 35MIN, 7±2, 510±220, 22±11                 </p>																																																																					
<p>Symbol signification</p> <ul style="list-style-type: none"> <li>★: indicate position of UVW channel</li> <li>☆: position to start counting ABZ channel</li> <li>▨: non-using zone</li> <li>HZ: high impedance</li> </ul>																																																																					

## ■ Electrical Characteristics

Parameter Item	Output type	OC	Voltage	Push-pull	TTL(26LS31)	TTL(26C31)	TTL(26C31) (Phase A,B,Z are back of phase U,V,W)	HTL(HD7)	
		Supply voltage		DC+5V±5% & DC8V-30V±5%			DC+5V±5%		DC8-30V±5%
Consumption current		100mA Max			120mA Max				
Allowable ripple		≤3%rms							
Top response frequency		100KHz			200KHz		300KHz		
Output capacity	Output current	Input	≤30mA	Load resistance 2.2K	≤30mA	≤±20mA		≤±50mA	
		Output	—		≤10mA				
	Output voltage	"H"	—	—	≥[ (Supply voltage) -2.5V]	≥2.5V		≥V <sub>cc</sub> -3 V <sub>DC</sub>	
		"L"	≤0.4V	≤0.7V(less than 20mA)	≤0.4V(30mA)	≤0.5V		≤ 1V V <sub>DC</sub>	
Load voltage	≤DC30V		—	—					
Rise & Fall time		Less than 2us(cable length: 2m)			Less than 1us(Cable length: 2m)		≤100ns		
Insulation strength		AC500V 60s							
Insulation resistance		10MΩ							
Mark to space ratio		45% to 55%							
Phase shift between A & B		90°±10° ( frequency in low speed )							
		90°±20° ( frequency in high speed )							
Origin motion		Low level available	High level available	Low level available	—	Low level available	—		
Delay motion time *		—				510±220ms		—	
GND		not connect to encoder							

\* Phase A,B,Z are back of phase U,V,W when power on.

## ■ Mechanical Characteristics

Shaft	Ø8mm(stainless)
Starting torque	Less than $5 \times 10^{-3} \text{N} \cdot \text{m}$
Inertia moment	Less than $3 \times 10^{-6} \text{kg} \cdot \text{m}^2$
Shaft load	Radial 50N; Axial 30N
Slew speed	≤3000 rpm; IP65≤2000 rpm
Bearing Life	$1.5 \times 10^9$ revs at rated load(100000hrs at 2500RPM)
Shell	Die cast aluminum
Weight	about 300g

## ■ Environmental Specifications

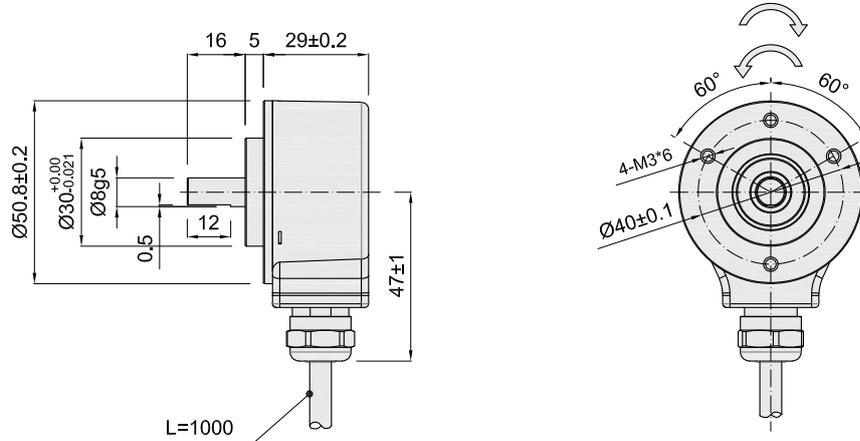
Environmental temperature	Operating: -20~+80°C(repeatable winding cable: -10°C); Storage: -25~+85°C
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(endure)	Amplitude 0.75mm,5~55Hz,2h for X,Y,Z direction individually
Shock(endure)	490m/s <sup>2</sup> 11ms three times for X,Y,Z direction individually
Protection	IP50; IP65

# S52

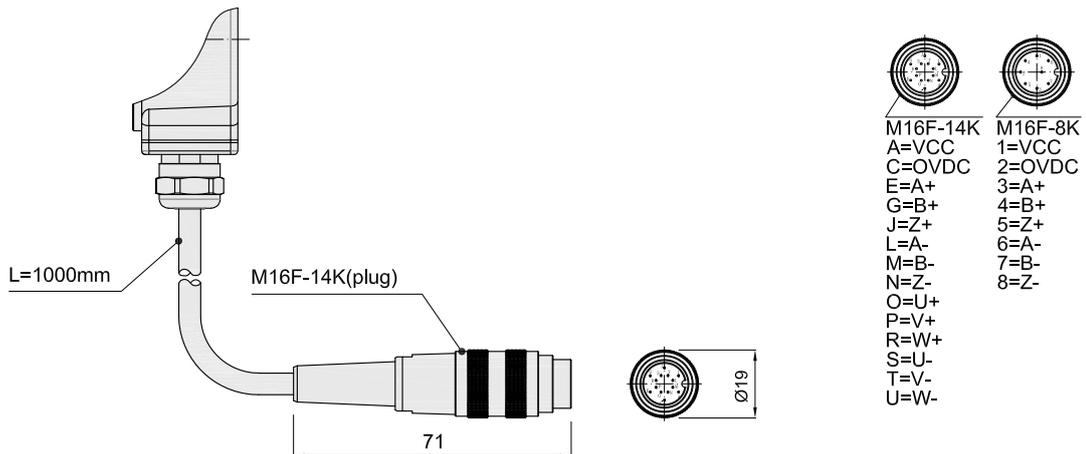
## Specifications 5/7

### Basic Dimensions

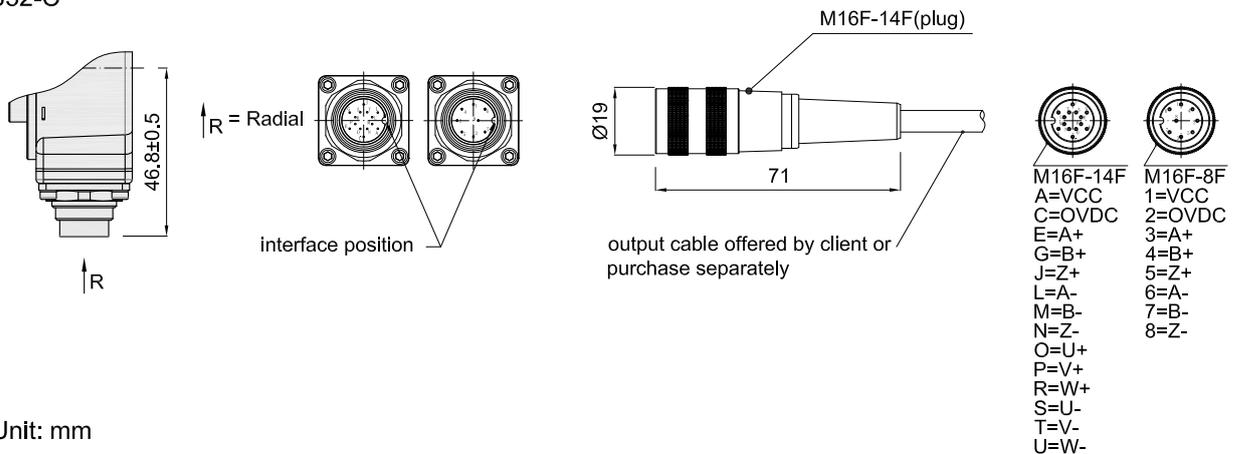
● S52-T



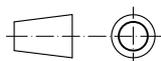
● S52-TE



● S52-C



Unit: mm

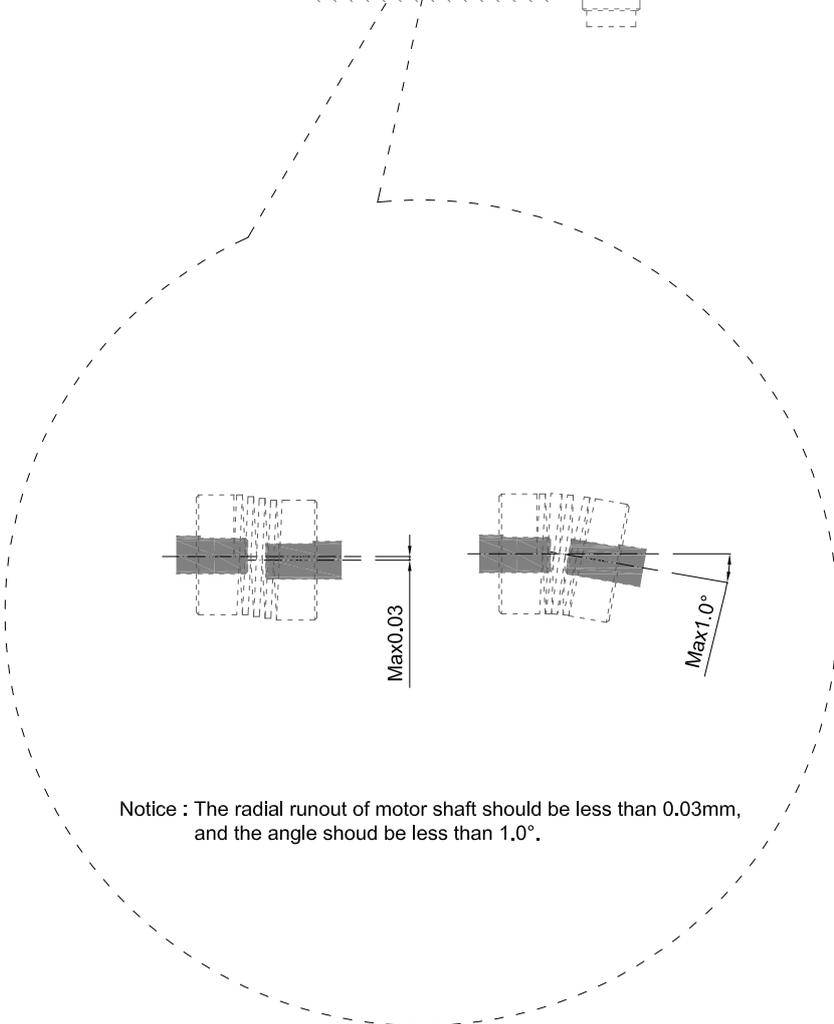
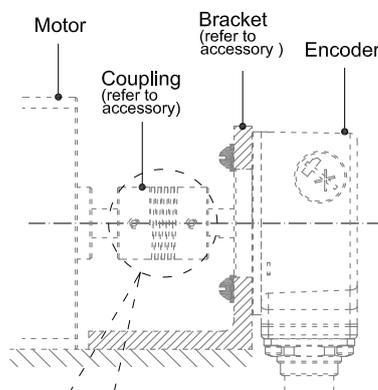


= The shaft rotary direction for encoder without UVW signal

= The shaft rotary direction for encoder with UVW signal

# S52 Specifications 6/7

## Assembling requirement



Notice : The radial runout of motor shaft should be less than 0.03mm, and the angle should be less than 1.0°.

### About vibration

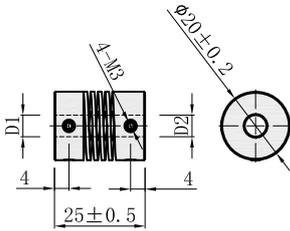
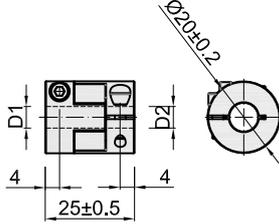
Vibration act on encoder always cause wrong pulse ,so we should pay attention to working place.

More pulse per revolution , narrower groovy spacing of grating ,more effect to encoder by vibration,when rev is low or stop , vibration act on shaft or main body would cause grating vibrating ,so encoder might make wrong pulse.

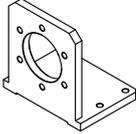
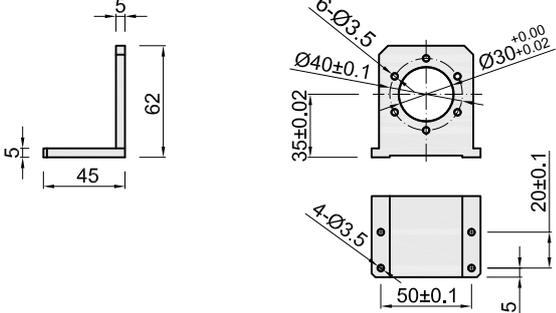
# S52 Specifications 7/7

■ Accessory(Need purchase additionally)

● Coupling

<p>H series spring coupling (general accuracy, or choose M series for higher accuracy)</p> <p>6H8 No:8700022 8H8 No:8700023 8H10 No:8700007</p>	 	<table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th>Model</th> <th>D1</th> <th>D2</th> </tr> </thead> <tbody> <tr> <td>6H8</td> <td><math>\varnothing 6^{+0.03}_{+0.01}</math></td> <td rowspan="2"><math>\varnothing 8^{+0.03}_{+0.01}</math></td> </tr> <tr> <td>8H8</td> <td rowspan="2"><math>\varnothing 8^{+0.03}_{+0.01}</math></td> </tr> <tr> <td>8H10</td> <td></td> <td><math>\varnothing 10^{+0.03}_{+0.01}</math></td> </tr> <tr> <td colspan="3" style="text-align: center;">material: aluminium alloy</td> </tr> </tbody> </table>	Model	D1	D2	6H8	$\varnothing 6^{+0.03}_{+0.01}$	$\varnothing 8^{+0.03}_{+0.01}$	8H8	$\varnothing 8^{+0.03}_{+0.01}$	8H10		$\varnothing 10^{+0.03}_{+0.01}$	material: aluminium alloy		
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<p>M series oldham coupling (high accuracy)</p> <p>6M8 No:8700038 8M8 No:8700039 8M10 No:8700040</p>	 	<table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th>Model</th> <th>D1</th> <th>D2</th> </tr> </thead> <tbody> <tr> <td>6M8</td> <td><math>\varnothing 6^{+0.03}_{+0.01}</math></td> <td rowspan="2"><math>\varnothing 8^{+0.03}_{+0.01}</math></td> </tr> <tr> <td>8M8</td> <td rowspan="2"><math>\varnothing 8^{+0.03}_{+0.01}</math></td> </tr> <tr> <td>8M10</td> <td></td> <td><math>\varnothing 10^{+0.03}_{+0.01}</math></td> </tr> <tr> <td colspan="3" style="text-align: center;">material: aluminium alloy</td> </tr> </tbody> </table>	Model	D1	D2	6M8	$\varnothing 6^{+0.03}_{+0.01}$	$\varnothing 8^{+0.03}_{+0.01}$	8M8	$\varnothing 8^{+0.03}_{+0.01}$	8M10		$\varnothing 10^{+0.03}_{+0.01}$	material: aluminium alloy		
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material: aluminium alloy																

● Bracket

<p>50L30 No:3500165</p>	 	<p>material: aluminium alloy</p>
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Unit: mm

